L Number	Hits	Search Text	DB	Time stamp
-	598	701/300.ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/17 16:32
-	706	(road and window$1) and gradient$1 and coordinat$5	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/17 16:13
-	537	((road and window$1) and gradient$1 and coordinat$5) and (accurac$5 or precision$5)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/17 16:14
-	676	((road and window$1) and gradient$1 and coordinat$5) and (accurac$5 or precision$5 or close$3 or metric$3 or match$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/17 16:14
-	4222	382/100,104;340/907;348/113;701/200,300.ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/18 18:47
-	30	382/100,104;340/907;348/113;701/200,300.ccls. and road and window$1 and gradient$1 and coordinates	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/18 18:52
-	9	(382/100,104;340/907;348/113;701/200,300.ccls. and road and window$1 and gradient$1 and coordinates) and ((vehicle or car or automobile) near4 lateral)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/18 18:52
-	5684	382/104,107,199,202;404/12,13,16;701/23,28,41;70.ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 07:10
-	1631	382/104,107,199,202;404/12,13,16;701/23,28,41;70.ccls. and road	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/19 19:21
-	309	(382/104,107,199,202;404/12,13,16;701/23,28,41;70.ccls. and road) and ((line or lane) near3 (determin$ or detect$4 or calcult$5))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/19 19:22

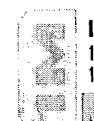|				
-	39	((382/104,107,199,202;404/12,13,16;701/23,28,41).ccls. and road) and ((line or lane) near3 (determin$ or detect$4 or calcult$5))) and gradient$1 and coordinate$1	US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/19 19:32
-	1428	road and ((line or lane) near7 recogni$8)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/19 19:33
-	15	(road and ((line or lane) near7 recogni$8)) and ((gradient and coordinate$1) same (lane or line))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/19 19:52
-	1414	382/100.ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/19 19:52
-	868	382/100.ccls. and (lane or line)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/19 19:53
-	41	(382/100.ccls. and (lane or line)) and road	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/19 19:53
-	5684	382/104,107,199,202;404/12,13,16;701/23,28,41;70.ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 06:47
-	241	382/104,107,199,202;404/12,13,16;701/23,28,41;70.ccls. and (road near4 line)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 07:10
-	5684	382/104,107,199,202;404/12,13,16;701/23,28,41;70.ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 07:11
-	329	382/104,107,199,202;404/12,13,16;701/23,28,41;70.ccls. and (road near3 (lane or line))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 07:18

-	24	(382/104,107,199,202;404/12,13,16;701/23,28,41;...).cls. and (road near3 (lane or line))) and gradient$1 and coordinate$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 07:12
-	1	(road near3 (lane or line)) and ((window$1 or display$1) near4 (gradient$1 and coordinate$1))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 07:21
-	505	((white near2 line$1) near4 (detect$5 or recogniz$6)) and road	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 07:22
-	25	(((white near2 line$1) near4 (detect$5 or recogniz$6)) and road) and gradient$1 and coordinate$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 07:22
-	0	intelligient near3 vehicle$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 07:31
-	26157	automatic near3 driv$4	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 07:32
-	29971	automatic near3 (driv$4 or steer$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 07:32
-	11917	(automatic near3 (driv$4 or steer$4)) and (lane or line)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 07:33
-	0	((automatic near3 (driv$4 or steer$4)) and (lane or line)) and gradient$1 and cordinate$1	USPAT; US-PGPUB; EPO; DERWENT; IBM_TDB	2004/09/20 07:34
-	4845369	o	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 07:34

-	156	((automatic near3 (driv$4 or steer$4)) and (lane or line)) and gradient$1 and coordinate$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/20 07:34

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vision system**
Jin-Woo Lee; Sung-Uk Choi; Young-Jin Lee; Lee, K.S.;
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2 **Image understanding based on edge histogram method for rear-en‹
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1994 , 31 Aug.-2 Sept. 1994
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6 **Finding and tracking road lanes using "line-snakes"**
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Pages:415 - 420

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3 **A study on recognition of lane and movement of vehicles for port Aı**
vision system
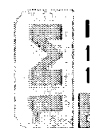*Jin Woo Lee; Jung Ho Kim; Young Jin Lee; Kwon Soon Lee;*
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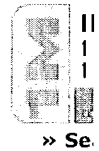   IEEE Member
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Solid-State Circuits Conference, 1998. Digest of Technical Papers. 45th ISSC(
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